

A HOMOGENIZED MODEL OF AN UNDERGROUND NUCLEAR WASTE REPOSITORY INCLUDING THE POSSIBLY DAMAGED ZONE

Eduard Marušić-Paloka ¹

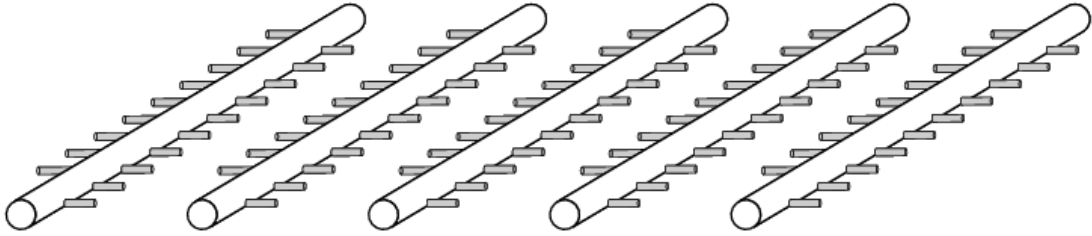


Figure 1: A part of a waste disposal unit, with 5 rows of containers and shafts

The Geometry

The whole domain: $\Omega =]0, L[\times] - L/2, L/2[\subset \mathbf{R}^3$

Middle surface (on which the repositories are located) : $\Sigma =]0, L[\times \{0\}$

Notations: $x = (x_1, x_2, x_3)$, $x' = (x_1, x_2)$, $y_i = x_i/\varepsilon$, $i = 2, 3$.

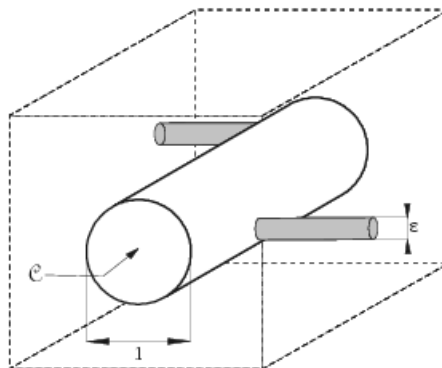


Figure 2: Cell of periodicity Y containing a shaft-damaged cylinder $S =] - 1/2, 1/2[\times \mathcal{C}$ and a containers P

¹Department of Mathematics, University of Zagreb, Bijenička 30, 10000 Zagreb, Croatia

The unit cell Y on figure ?? consists of three parts:

- The shaft-damaged cylinder $\mathcal{S} =] - 1/2, 1/2[\times \mathcal{C}$ with basis \mathcal{C}
- The containers P
- The rest of the cell \mathcal{Y}

By the change of variable $y = x/\varepsilon$ we shrink the unit cell Y to the actual size ε and we denote by

$$Y_\varepsilon(i, j) = \varepsilon ((i, j, 0) + Y)$$

the (i, j) -th ε -cell.

Inside these ε -cell:

- $\mathcal{P}_\varepsilon(i, j) = \varepsilon ((i, j, 0) + P) =$ **the containers set**
- $\mathcal{S}_\varepsilon(i, j) = \varepsilon ((i, j, 0) + \mathcal{S}) =$ **the shaft-damaged part**

Repeating Y_ε periodically over the surface Σ , we obtain the whole repository area and we denote :

$$\mathcal{P}_\varepsilon = \bigcup_{i,j=1}^m \varepsilon ((i, j, 0) + P) \quad \text{the union of all containers sets}$$

$$\mathcal{S}_\varepsilon = \bigcup_{i,j=1}^m \varepsilon ((i, j, 0) + \mathcal{S}) \quad \text{the union of all shaft-damaged cylinders}$$

$$\mathcal{C}_\varepsilon = \bigcup_{i,j=1}^m \varepsilon ((i, j) + \mathcal{C}) \quad \text{the union of all shaft-damaged cylinders sections.}$$

The exterior boundary $S = \partial\Omega$ is divided in three parts:

$$\mathcal{F}_\varepsilon = \mathcal{S}_\varepsilon \cap \{x_1 = L\} \quad \text{the front of the shaft-damaged cylinders} \quad (1)$$

$$\mathcal{B}_\varepsilon = \mathcal{S}_\varepsilon \cap \{x_1 = 0\} \quad \text{the back of the shaft-damaged cylinders} \quad (2)$$

$$\mathcal{R}_\varepsilon = \mathcal{S}_\varepsilon \setminus (\mathcal{F}_\varepsilon \cup \mathcal{B}_\varepsilon) \quad \text{the rest of the exterior boundary of } \Omega \quad (3)$$

The equations

$f^\varepsilon \in C([0, T] \times \Omega)$ - the function describing the sources (it has a compact support in time $[0, t_m] \subset]0, T[$ and in space \mathcal{P}_ε .)

$\lambda = \frac{\log 2}{\tau} > 0$, with τ being the half life of the radioactive element.

$\varphi_0 \in L^\infty(\Omega)$ - the initial concentration of the radioactive material in the soil.

The convection velocity $\mathbf{v}^\varepsilon = (v_1^\varepsilon, v_2^\varepsilon, v_3^\varepsilon)$ is larger in the shaft than in the host rock. Thus we suppose that it has the form

$$\mathbf{v}^\varepsilon(x) = \begin{cases} \mathbf{v}^h(x) & \text{in the clay } \Omega \setminus \mathcal{S}_\varepsilon \\ \varepsilon^{-\beta} \mathbf{v}^d(x', x_2/\varepsilon, x_3/\varepsilon) & \text{in the shaft } \mathcal{S}_\varepsilon \end{cases} .$$

We suppose for simplicity of this presentation that the convection velocity in shafts is unidirectional, i.e. that $\mathbf{v}^d = v^d(x_2, x_2/\varepsilon, x_3/\varepsilon) \mathbf{e}_1$.

The effective diffusion/dispersion tensor:

$$\mathbf{A}^\varepsilon = d \mathbf{I} + |\mathbf{v}^\varepsilon| \alpha^\varepsilon \mathbf{E}(\mathbf{v}^\varepsilon) ,$$

with

$$[\mathbf{E}(\mathbf{v}^\varepsilon)]_{ij} = \frac{v_i^\varepsilon v_j^\varepsilon}{|\mathbf{v}^\varepsilon|^2}$$

and

$$\alpha^\varepsilon = \begin{cases} \alpha^h & \text{in the host rock } \Omega \setminus \mathcal{S}_\varepsilon \\ \alpha^d & \text{in the shaft } \mathcal{S}_\varepsilon \end{cases} , \quad .$$

We assume that

$$d(x) \geq d_0 > 0 \quad . \quad (4)$$

Thus

$$\mathbf{A}^\varepsilon(x) = \begin{cases} \mathbf{A}^h(x) & \text{in the host rock } \Omega \setminus \mathcal{S}_\varepsilon \\ d(x) \mathbf{I} + \varepsilon^{-\beta} \mathbf{A}^d(x_2, x_2/\varepsilon, x_3/\varepsilon) & \text{in the shaft } \mathcal{S}_\varepsilon \end{cases} .$$

Due to our assumption that the convection in shafts goes only in the direction of the shaft, **matrix \mathbf{A}^d now has the form:**

$$\mathbf{A}^d(x_2, y_2, y_3) = |v^d|(x_2, y_2, y_3) (\mathbf{e}_1 \otimes \mathbf{e}_1)$$

Finally the porosity ω^ε is also larger in the shaft than in the host rock but the discrepancy is not so large as for the permeability

$$\omega^\varepsilon = \begin{cases} \omega^h & \text{in the host rock } \Omega \setminus \mathcal{S}_\varepsilon \\ \omega^d & \text{in the shaft } \mathcal{S}_\varepsilon \end{cases} .$$

The problem:

$$\omega^\varepsilon \frac{\partial \varphi_\varepsilon}{\partial t} - \operatorname{div}(\mathbf{A}^\varepsilon \nabla \varphi_\varepsilon) + (\mathbf{v}^\varepsilon \cdot \nabla) \varphi_\varepsilon + \lambda \omega^\varepsilon \varphi_\varepsilon = f^\varepsilon \quad \text{in } \Omega^T \quad (5)$$

$$\varphi_\varepsilon(0, x) = \Phi_0(x) \quad x \in \Omega \quad (6)$$

$$(7)$$

We also need to impose some **boundary condition on the exterior boundary** $S = \partial\Omega$:

$$\mathbf{n} \cdot (\mathbf{A}^\varepsilon \nabla \varphi_\varepsilon - \mathbf{v}^\varepsilon \varphi_\varepsilon) = \kappa (\varphi_\varepsilon - g_\varepsilon) \quad \text{on } \mathcal{R}_\varepsilon^T \cup \mathcal{F}_\varepsilon^T \quad \text{-- the Fourier law} \quad (8)$$

$$\varphi_\varepsilon = 0 \quad \text{on } \mathcal{B}_\varepsilon^T \quad \text{-- back side is sealed} \quad (9)$$

$g_\varepsilon \in L^2(0, T; L^2(S))$ -the trace of the exterior concentration

$\kappa \in L^\infty(S)$, $0 < \kappa_0 \leq \kappa(x) \leq \kappa_1$ the rate of proportionality in the Fourier law.

Results:

Depending on β we distinguish 3 different cases :

$\beta < 1$ This is the simplest case when the shafts do not make any contribution, i.e. the repository behaves as if they were not there.

$\beta = 1$ This is the most interesting case when the processes in the shaft and out of it are of the same order of intensity and there is an interaction between them.

$\beta > 1$ In this case the process in the shafts is dominant and we do not see the rest of the domain in the limit.

A priori estimates

Proposition 1 *Let $\{\varphi_\varepsilon\}$ be the sequence of solutions to the problem (??)-(??). Then there exists a constant $C > 0$, independent from ε , such that*

$$|\nabla\varphi_\varepsilon|_{L^2(0,T;L^2(\Omega))} \leq C \tag{10}$$

$$|\varphi_\varepsilon|_{L^\infty(0,T;L^2(\Omega))} \leq C \tag{11}$$

$$|\varphi_\varepsilon|_{L^2(0,T;L^2(\mathcal{S}_\varepsilon))} \leq C \varepsilon^{\beta/2} \tag{12}$$

$$\left| \frac{\partial\varphi_\varepsilon}{\partial x_1} \right|_{L^2(0,T;L^2(\mathcal{S}_\varepsilon))} \leq C \varepsilon^{\beta/2} . \tag{13}$$

The simplest case $\beta < 1$

The source: $f^\varepsilon(t, x) = \frac{1}{\varepsilon} f(t, \frac{x}{\varepsilon})$, $(y_1, y_2) \mapsto f(t, y_1, y_2, y_3)$ is 1- periodic $\text{supp } f \subset P \times [0, t_m]$

Theorem 1 *Let $\beta < 1$ and let $\{\varphi_\varepsilon\}$ be the sequence of solutions to the problem (??)-(??). Then*

$$\varphi_\varepsilon \rightharpoonup \varphi \quad \text{weak* in } L^\infty(0, T; L^2(\Omega)) \text{ and weakly in } L^2(0, T; H^1(\Omega)) \quad , \tag{14}$$

where φ is the unique solution of the problem

$$\omega^h \frac{\partial\varphi}{\partial t} - \text{div}(\mathbf{A}^h \nabla\varphi) + (\mathbf{v}^h \cdot \nabla)\varphi + \lambda \omega^h \varphi = \bar{f} \delta_\Sigma \quad \text{in } \tilde{\Omega}^T = (\Omega \setminus \Sigma) \times]0, T[\tag{15}$$

$$\varphi(x, 0) = \Phi_0(x) \quad x \in \tilde{\Omega} = \Omega \setminus \Sigma \quad , \quad \varphi = 0 \quad \text{on } S^T \tag{16}$$

$$\tag{17}$$

$$\bar{f} = \int_P f \, dy \quad .$$

The critical case $\beta = 1$

In this case the contributions from shafts and those from host rock are of the same order. Thus they both appear in the limit problem. We assume again that f^ε is of the same form $f^\varepsilon(t, x) = \frac{1}{\varepsilon} f(t, \frac{x}{\varepsilon})$.

$$g_\varepsilon = \begin{cases} g^h & \text{in the host rock } \mathcal{R}_\varepsilon \\ \varepsilon^{-1} g^d & \text{in the shaft } \mathcal{F}_\varepsilon \end{cases} . \quad (18)$$

Two-scale convergence with respect to the singular measure:

In order to see some effects of the process that is going on in thin domain \mathcal{S}_ε we need to consider the limit with respect to the rescaled measure $d\mu^\varepsilon(x) = \varepsilon^{-1} \mathbf{1}_{\mathcal{S}_\varepsilon} d\mathcal{L}_3$, where $d\mathcal{L}_3$ is the Lebesgue measure :

Definition 1 A sequence $\{\varphi_\varepsilon\}_{\varepsilon>0}$, $\varphi_\varepsilon \in L^p(\Omega)$ is said to converge two-scale to $\varphi_0 \in L^2(\Sigma \times \mathcal{C})$ if for any $\psi \in C(\Omega; L^p(\mathcal{C}))$

$$\lim_{\varepsilon \rightarrow 0} \int_{\Omega} \varphi_\varepsilon(x) \psi(x, \frac{x_2}{\varepsilon}, \frac{x_3}{\varepsilon}) d\mu^\varepsilon(x) = \int_{\Omega} d\delta_\Sigma(x) \int_{\mathcal{C}} \varphi_0(x_1, x_2, y_2, y_3) \psi(x, y) dy_2 dy_3 , \quad (19)$$

In other words (??) can be simply written as

$$\lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \int_{\mathcal{S}_\varepsilon} \varphi_\varepsilon(x) \psi(x, \frac{x'}{\varepsilon}) dx = \int_{\Sigma} dx_1 dx_2 \int_{\mathcal{C}} \varphi_0(x_1, x_2, y) \psi(x_1, x_2, 0, y_2, y_3) dy .$$

We denote shortly

$$\varphi_\varepsilon \xrightarrow{2-d\mu} \varphi_0$$

Theorem 2 Let $\beta = 1$ and let $\{\varphi_\varepsilon\}$ be the sequence of solutions to the problem (??)-(??). Then

$$\varphi_\varepsilon \rightharpoonup \varphi \quad \text{weak* in } L^\infty(0, T; L^2(\Omega)) \text{ and weakly in } L^2(0, T; H^1(\Omega)) , \quad (20)$$

$$\varphi_\varepsilon \xrightarrow{2-d\mu} \varphi(t, x_1, x_2, 0) \quad \text{two scale} , \quad (21)$$

where φ is the unique solution of the following variational problem :

Find $\varphi \in L^2(0, T; V)$, such that

$$\begin{aligned} & \int_0^T \int_{\Omega} \left(-\omega^h \varphi \frac{\partial \psi}{\partial t} + \mathbf{A}^h \nabla \varphi \nabla \psi + (\mathbf{v}^h \cdot \nabla) \varphi \psi + \lambda \omega^h \varphi \psi \right) + \int_{S^T} \kappa \varphi \psi + \\ & + \int_0^T \int_{\Sigma} \left(\langle |v^d| \rangle \frac{\partial \varphi}{\partial x_1}(t, x', 0) \frac{\partial \psi}{\partial x_1}(t, x', 0) + \langle v^d \rangle \frac{\partial \varphi}{\partial x_1}(t, x', 0) \psi(t, x', 0) \right) = \\ & = \int_0^T \int_{\Sigma} \bar{f} \psi(t, x', 0) + \int_{\Omega} \omega^h \Phi_0 \psi(0, x) + \int_{S^T} \kappa \psi g^h + \int_0^T \int_0^L \kappa \psi(t, L, x_2, 0) g^d , \\ & \text{for any } \psi \in H^1(0, T; V) \text{ such that } \psi(T, x) = 0 . \end{aligned} \quad (22)$$

$$V = \{ \phi \in H^1(\Omega) ; \frac{\partial}{\partial x_1} \phi(x_1, x_2, 0) \in L^2(\Sigma) , \phi(0, x_2, 0) = 0 \} , \quad \langle z \rangle = \int_{\mathcal{C}} z \, dy_2 \, dy_3 .$$

Remark 1 In case of non-diagonal \mathbf{A}^d , i.e. non-unidirectional convection in shafts, it is necessary to introduce R , the solution of the auxiliary problem

$$\begin{aligned} \operatorname{div}_y (\mathbf{A}^d \nabla_y R) &= -\operatorname{div}_y (\mathbf{A}^d \mathbf{e}_1) \quad \text{in } \mathcal{C} \\ \mathbf{n} \cdot \mathbf{A}^d \nabla_y R &= -\mathbf{n} \cdot \mathbf{A}^d \mathbf{e}_1 \quad \text{on } \partial \mathcal{C} . \end{aligned} \quad (23)$$

to describe the oscillatory part of the two scale limit φ_1 which has the form

$$\varphi_1 = R(y) \frac{\partial \varphi_0}{\partial x_1} .$$

Then the coefficient $\langle |v^d| \rangle$ in the above problem must be replaced by $\langle \mathbf{A}^d \nabla_y (y_1 + R) \rangle$. In case of diagonal matrix \mathbf{A}^d the solution of the auxiliary (??) is trivial $R = 0$.

The case of dominant shafts $\beta > 1$

In this last case the conductivity of shafts is so high that the process inside is dominant in the global scale. We assume that the behavior of g_ε is as follows:

$$g_\varepsilon = \begin{cases} g^h & \text{on the host rock } \mathcal{R}_\varepsilon \\ \varepsilon^{-\frac{\beta+1}{2}} g^d & \text{on the shaft } \mathcal{F}_\varepsilon \end{cases} . \quad (24)$$

Remark 2 We notice that in case $\beta = 1$ condition (??) reduces to the previously imposed condition on g_ε .

Theorem 3 Let $\beta > 1$ and let $\{\varphi_\varepsilon\}$ be the sequence of solutions to the problem (??)-(??). Then there exist a subsequence, denoted by the same symbol $\{\varphi_\varepsilon\}$ and an accumulation point $\varphi^0 \in \mathcal{W} = \{ \phi \in L^2(\Sigma \times \mathcal{C}) ; \frac{\partial \phi}{\partial x_1} \in L^2(\Sigma \times \mathcal{C}) \}$ such that

$$\varepsilon^{\frac{1-\beta}{2}} \varphi_\varepsilon \xrightarrow{2-d\mu} \varphi^0 \quad \text{two scale} \quad (25)$$

$$\varepsilon^{\frac{1-\beta}{2}} \frac{\partial \varphi_\varepsilon}{\partial x_1} \xrightarrow{2-d\mu} \frac{\partial \varphi^0}{\partial x_1} \quad \text{two scale} . \quad (26)$$

For $1 < \beta < 2$, function φ^0 is the unique solution of the problem :

$$\begin{aligned} -\frac{\partial}{\partial x_1} \left(\langle |v^d| \rangle \frac{\partial \varphi^0}{\partial x_1} \right) + \langle v^d \rangle \frac{\partial \varphi^0}{\partial x_1} &= 0 \quad \text{in }]0, L[\\ \varphi^0(0) = 0 \quad , \quad -\langle |v^d| \rangle \frac{\partial \varphi^0}{\partial x_1}(L) + (\langle v^d \rangle + \kappa) \varphi^0(L) &= \kappa \langle g^d \rangle . \end{aligned} \quad (27)$$

This problem can be solved explicitly and

$$\varphi^0 = \frac{\langle g^d \rangle}{1 + \frac{\langle v^d \rangle}{\kappa} - e^{\text{sgn}(v^d) L}} (1 - e^{\text{sgn}(v^d) x_1}) \quad (28)$$

For $\beta > 2$, function φ^0 is the unique solution of the problem :

$$\begin{aligned} -\frac{\partial}{\partial x_1} \left(|v^d| \frac{\partial \varphi^0}{\partial x_1} \right) + v^d \frac{\partial \varphi^0}{\partial x_1} &= 0 \quad \text{in }]0, L[\\ \varphi^0(0) &= 0 \quad , \quad -|v^d| \frac{\partial \varphi^0}{\partial x_1}(L) + (v^d + \kappa) \varphi^0(L) = \kappa g^d \quad . \end{aligned} \quad (29)$$

This problem can be solved explicitly too and

$$\varphi^0 = \frac{g^d}{1 + \frac{v^d}{\kappa} - e^{\text{sgn}(v^d) L}} (1 - e^{\text{sgn}(v^d) x_1}) \quad (30)$$

In case $\beta = 2$ and v^d independent on y , we have the convergence of mean concentrations in the shafts:

$$\frac{1}{\varepsilon} \int_{\mathcal{S}_\varepsilon} \varepsilon^{\frac{1-\beta}{2}} \varphi_\varepsilon \rightharpoonup \langle \varphi^0 \rangle \quad \text{weakly in } H^1(0, L) \quad . \quad (31)$$

where

$$\varphi^0 = \frac{\langle g^d \rangle}{1 + \frac{v^d}{\kappa} - e^{\text{sgn}(v^d) L}} (1 - e^{\text{sgn}(v^d) x_1}) \quad (32)$$

Remark 3 Actually, using the two-scale convergence, we can prove that, up to a subsequence $\varphi_\varepsilon \xrightarrow{2-d\mu} \varphi^0$ where φ^0 satisfies the partial differential equation

$$-d \Delta_{y_2 y_3} \varphi^0 - |v^d| \frac{\partial^2 \varphi^0}{\partial x_1^2} + v^d \frac{\partial \varphi^0}{\partial x_1} = 0$$

in $]0, L[\times \mathcal{C}$ but we cannot identify the boundary conditions that it satisfies on $]0, L[\times \partial \mathcal{C}$. Thus, we cannot prove the uniqueness of the accumulation point.